20210415

* The yaw angle return to zero logic need to be added
* The load cell, potentiometer and IMU need to be calibrated, spring stiffness also need to be calibrated
* IMU need to check if it is 6 axis or 9 axis
* System parameter and motor + driver actuation unit parameter calibration

20210521

* High-level controller end condition
* The time-up stop condition for timer-loop need to be determined
* Initialization logic for Ready signal receiving √
* Sensor feedback showing in MATLAB
* Stop commanded in MATLAB
* High-level and low-level handshake process